

I-Telegraphie:

a) $\frac{1}{2}(1 + e^{-2\gamma(t_2-t_1)}) \equiv$ proba. de estar das le m etat. (0,5)
 $\frac{1}{2}(1 - e^{-2\gamma(t_2-t_1)}) \equiv$ proba de quitter l'etat.

b) $\sum_{n_2} p(n_2, t_2 | n_1, t_1) = \sum_{n_2} \frac{1}{2}(1 + e^{-2\gamma(t_2-t_1)}) \delta_{n_2, n_1} + \frac{1}{2}(1 - e^{-2\gamma(t_2-t_1)}) \delta_{n_2, -n_1}$
 $= \frac{1}{2}(1 + e^{-2\gamma(t_2-t_1)}) + \frac{1}{2}(1 - e^{-2\gamma(t_2-t_1)}) \delta_{n_2, -n_1}$
 $= 1.$ (0,5)

c) $\sum_{n_1'} p(n_2, t_2 | n_1', t_1) p(n_1', t_1 | n_1, t_1)$
 $= \sum_{n_1'} \left[\frac{1}{2}(1 + e^{-2\gamma(t_2-t_1)}) \delta_{n_2, n_1'} + \frac{1}{2}(1 - e^{-2\gamma(t_2-t_1)}) \delta_{n_2, -n_1'} \right]$
 $\left[\frac{1}{2}(1 + e^{-2\gamma(t_1-t_2)}) \delta_{n_1', n_1} + \frac{1}{2}(1 - e^{-2\gamma(t_1-t_2)}) \delta_{n_1', -n_1} \right]$
 $= \frac{1}{4}(1 + e^{-2\gamma(t_2-t_1)})(1 + e^{-2\gamma(t_1-t_2)}) \delta_{n_2, n_1} +$
 $\frac{1}{4}(1 - e^{-2\gamma(t_2-t_1)})(1 + e^{-2\gamma(t_1-t_2)}) \delta_{n_2, -n_1} +$
 $\frac{1}{4}(1 + e^{-2\gamma(t_2-t_1)})(1 - e^{-2\gamma(t_1-t_2)}) \delta_{n_2, -n_1} +$
 $\frac{1}{4}(1 - e^{-2\gamma(t_2-t_1)})(1 - e^{-2\gamma(t_1-t_2)}) \delta_{n_2, n_1}$
 $= \frac{1}{4} \left(\frac{1 + e^{-2\gamma(t_2-t_1)}}{+e} \frac{1 + e^{-2\gamma(t_1-t_2)}}{+e} \frac{1 + e^{-2\gamma(t_2-t_1)}}{+e} + \right.$
 $\left. \frac{1 + e^{-2\gamma(t_2-t_1)}}{+e} \frac{1 + e^{-2\gamma(t_1-t_2)}}{-e} \frac{1 + e^{-2\gamma(t_2-t_1)}}{+e} \right) \delta_{n_2, n_1}$
 $+ \frac{1}{4} \left(\frac{1 - e^{-2\gamma(t_2-t_1)}}{+e} \frac{1 + e^{-2\gamma(t_1-t_2)}}{-e} \frac{1 - e^{-2\gamma(t_2-t_1)}}{-e} \right.$
 $\left. + \frac{1 + e^{-2\gamma(t_2-t_1)}}{-e} \frac{1 + e^{-2\gamma(t_1-t_2)}}{+e} \frac{1 - e^{-2\gamma(t_2-t_1)}}{-e} \right) \delta_{n_2, -n_1}$

$$= \frac{1}{2} (1 + e^{-2\gamma(t_2-t_1)}) \delta_{n_1, n_2} + \frac{1}{2} (1 - e^{-2\gamma(t_2-t_1)}) \delta_{n_1, -n_2} \quad \textcircled{15}$$

d) On a:

$$p_1^{\circ} = \sum_n w_{n_1 n} p_n = \sum_n w_{n n_2} p_n$$

$$= w_{n_1 n_2} p_2 - w_{n_2 n_1} p_1$$

$$\text{or } w_{n_1 n_2} = \lim_{\Delta t \rightarrow 0} \frac{1}{2} \left[\frac{2\gamma \Delta t}{\Delta t} \right] = \gamma = w_{n_2 n_1}$$

$$\Rightarrow \begin{cases} p_1^{\circ} = \gamma (p_2 - p_1) \\ p_2^{\circ} = \gamma (p_1 - p_2) \end{cases} \quad \textcircled{1}$$

$$e) \begin{cases} p_1^{\circ} = -\gamma p_1 + \gamma p_2 \\ p_{-1}^{\circ} = -\gamma p_{-1} + \gamma p_1 \end{cases} \quad \text{avec } p_1 + p_{-1} = 1$$

$$\Rightarrow p_1^{\circ} = -\gamma p_1 + \gamma [1 - p_1] = -2\gamma p_1 + \gamma$$

$$\Rightarrow p_1(t) = \lambda e^{-2\gamma t} + \frac{1}{2}$$

$$\text{or } p_1(t=0) = 1 = 0 \quad \lambda + \frac{1}{2} = 1 \Rightarrow \lambda = \frac{1}{2}$$

$$\begin{cases} p_1(t) = \frac{1}{2} (1 + e^{-2\gamma t}) \end{cases} \quad \textcircled{1}$$

$$\begin{cases} p_2(t) = 1 - p_1(t) = \frac{1}{2} (1 - e^{-2\gamma t}) \end{cases}$$

$$p_n(t) = \frac{1}{2} (1 + e^{-2\gamma t}) \delta_{n, 1} + \frac{1}{2} (1 - e^{-2\gamma t}) \delta_{n, -1} \quad \textcircled{0,5}$$

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$$f) p(n, t) = \frac{1}{2} (1 + e^{-2\gamma t}) \delta_{n,1} + \frac{1}{2} (1 - e^{-2\gamma t}) \delta_{n,-1}.$$

$$p(n_2, t_2) = \sum_{n_1} p(n_2, t_2 | n_1, t_1) p(n_1, t_1)$$

$$= \sum_{n_1} \left[\frac{1}{2} (1 + e^{-2\gamma(t_2-t_1)}) \delta_{n_2, n_1} + \frac{1}{2} (1 - e^{-2\gamma(t_2-t_1)}) \delta_{n_2, -n_1} \right]$$

$$\left[\frac{1}{2} (1 + e^{-2\gamma t_1}) \delta_{n_1, 1} + \frac{1}{2} (1 - e^{-2\gamma t_1}) \delta_{n_1, -1} \right]$$

$$= \frac{1}{4} \left[1 + e^{-2\gamma(t_2-t_1)} + e^{-2\gamma t_1} + e^{-2\gamma t_2} \right] \underbrace{\delta_{n_1, n_2} \delta_{n_1, 1}}_{\delta_{n_2, 1}}$$

$$+ \frac{1}{4} \left[1 - e^{-2\gamma(t_2-t_1)} + e^{-2\gamma t_1} - e^{-2\gamma t_2} \right] \underbrace{\delta_{n_1, -n_2} \delta_{n_1, 1}}_{\delta_{n_2, -1}}$$

$$+ \frac{1}{4} \left[1 + e^{-2\gamma(t_2-t_1)} - e^{-2\gamma t_1} - e^{-2\gamma t_2} \right] \underbrace{\delta_{n_1, n_2} \cdot \delta_{n_1, -1}}_{\delta_{n_2, -1}}$$

$$+ \frac{1}{4} \left[1 - e^{-2\gamma(t_2-t_1)} - e^{-2\gamma t_1} + e^{-2\gamma t_2} \right] \underbrace{\delta_{n_1, -n_2} \delta_{n_1, -1}}_{\delta_{n_2, 1}}$$

$$= \frac{1}{4} \left[2 + 2 e^{-2\gamma t_2} \right] \delta_{n_2, 1} + \frac{1}{4} \left[2 - 2 e^{-2\gamma t_2} \right] \delta_{n_2, -1}.$$

$$= \frac{1}{2} \left[1 + e^{-2\gamma t_2} \right] \delta_{n_2, 1} + \frac{1}{2} \left[1 - e^{-2\gamma t_2} \right] \delta_{n_2, -1}.$$

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(4)

II - Potentiel harmonique.

a) $\langle P(t) \rangle = 0$ moyenne nulle, pas de direction privilégiée
 $\langle P(t) P(t') \rangle$ pas de mémoire du bruit. (0,5)
 impatance \Rightarrow Markov.

b) régime visqueux: $|m \gamma \frac{dx}{dt}| \gg |m \frac{d^2x}{dt^2}|$

$\Rightarrow 0 = -m \gamma \frac{dx}{dt} - \frac{dL(x)}{dx} + m P(t)$

$\Rightarrow \boxed{\frac{dx}{dt} = - \frac{1}{m \gamma} \frac{dL(x)}{dx} + \frac{1}{\gamma} P(t)}$ (0,5)

c) On a: $\frac{dp(x,t)}{dt} = - \frac{\partial}{\partial x} [a_1 p(x,t)] + \frac{\partial^2}{\partial x^2} [a_2 p(x,t)]$

$a_1(x,t) = \int dx' (x' - x) p(x', t' | x, t)$ (1)

$a_2(x,t) = \frac{1}{2} \int dx' (x' - x)^2 p(x', t' | x, t)$

d) On a: $x(t + \Delta t) - x(t) = \int_t^{t+\Delta t} - \frac{1}{m \gamma} \frac{dL(x)}{dx} + \frac{1}{\gamma} P(t) dt$
 $= - \frac{\Delta t}{m \gamma} \frac{dL(x)}{dx} + \frac{1}{\gamma} \int_t^{t+\Delta t} P(t) dt$

$\Rightarrow \langle x(t + \Delta t) - x(t) \rangle = - \frac{\Delta t}{m \gamma} \frac{dL(x)}{dx}$

et $\boxed{a_1(x,t) = - \frac{1}{m \gamma} \frac{dL(x)}{dx}}$ (0,5)

⑥

$$= - \int dx x^n n x^{n-1} \frac{1}{m\gamma} k x p + \frac{D}{\gamma^2} n x^{n-1} \frac{\partial p}{\partial x}$$

$$= - \frac{k}{m\gamma} \langle x^n \rangle - \frac{Dn}{\gamma^2} \int x^{n-1} \frac{\partial p}{\partial x}$$

$$= - \frac{k}{m\gamma} n \langle x^n \rangle + \frac{D}{\gamma^2} n(n-1) \int x^{n-2} p$$

$$= - \frac{k}{m\gamma} n \langle x^n \rangle + \frac{D}{\gamma^2} n(n-1) \langle x^{n-2} \rangle$$

①

b) $n=1$

$$\frac{d}{dt} \langle x \rangle = - \frac{k}{m\gamma} \langle x \rangle$$

$$\Rightarrow \langle x(t) \rangle = \lambda e^{-\frac{k}{m\gamma} t}$$

$$\text{or } p(x, t=0) = \delta(x-x_0)$$

$$\Rightarrow \langle x(t=0) \rangle = \int dx x p(x, t=0) = x_0$$

$$\Rightarrow \lambda = x_0$$

$$\langle x(t) \rangle = x_0 e^{-\frac{k}{m\gamma} t}$$

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$$\frac{d}{dt} \langle x^2 \rangle = - \frac{2k}{m\gamma} \langle x^2 \rangle + \frac{2D}{\gamma^2}$$

$$\Rightarrow \langle x^2(t) \rangle = d e^{-\frac{2k}{m\gamma} t} + \frac{2D m\gamma}{\gamma^2 2k} = d e^{-\frac{2k}{m\gamma} t} + \frac{Dm}{\gamma k}$$

$$\langle x^2(t=0) \rangle = x_0^2 = d + \frac{mD}{\gamma k} \Rightarrow d = x_0^2 - \frac{mD}{\gamma k} \quad (7)$$

$$\Rightarrow \langle x^2(t) \rangle = \left(x_0^2 - \frac{mD}{\gamma k} \right) e^{-\frac{2k}{m\gamma} t} + \frac{mD}{\gamma k}$$

$\xrightarrow{\hspace{2cm}} \frac{mD}{\gamma k}$

$$\text{or } \langle \frac{1}{2} k x^2 \rangle = \frac{1}{2} k_B T = \frac{1}{2} \frac{mDk}{\gamma k} = \frac{mD}{2\gamma}$$

$$\Rightarrow \boxed{k_B T = \frac{mD}{\gamma}} \quad (0,5)$$

$$\begin{aligned} \text{c) } \frac{dM_n(t)}{dt} &= \frac{d}{dt} \int p_n(x,t) [x - \langle x(t) \rangle]^n \\ &= \int \frac{dp_n(x,t)}{dt} [x - \langle x(t) \rangle]^n \\ &\quad + \int p_n(x,t) n [x - \langle x(t) \rangle]^{n-1} \left[- \frac{d\langle x(t) \rangle}{dt} \right] \end{aligned}$$

$$= \int \frac{\partial}{\partial x} \left[\frac{k}{m\gamma} x p + \frac{D}{\gamma^2} \frac{\partial p}{\partial x} \right] [x - \langle x(t) \rangle]^n$$

$$- \int p n [x - \langle x(t) \rangle]^{n-1} \left[- \frac{k}{\gamma m} \langle x \rangle \right]$$

$$= - \int \frac{k}{\gamma m} x p n [x - \langle x(t) \rangle]^{n-1} + \int \frac{k n \langle x \rangle}{\gamma m} p [x - \langle x \rangle]^{n-1}$$

$$+ \int \frac{D}{\gamma^2} p n [n-1] [x - \langle x \rangle]^{n-2}$$

$$= - \frac{k n}{\gamma m} [x - \langle x(t) \rangle]^n + \frac{D}{\gamma^2} n [n-1] [x - \langle x \rangle]^{n-2}$$

$$= - \frac{k n}{\gamma m} M_n(t) + \frac{D}{\gamma^2} n (n-1) M_{n-2}(t) \quad (1,5)$$

$$\text{On a } \textcircled{1} \quad M_n'(t) = -\frac{k_n}{\gamma m} M_n(t) + \frac{D}{\gamma^2} n(n-1) M_{n-2}(t) \quad \textcircled{8}$$

$$M_n(t) = \lambda_n(t) e^{-\frac{k_n}{\gamma m} t}$$

$$M_n'(t) = \lambda_n'(t) e^{-\frac{k_n}{\gamma m} t} = \frac{D}{\gamma^2} n(n-1) M_{n-2}(t)$$

$$\Rightarrow \lambda_n'(t) = \frac{D}{\gamma^2} n(n-1) e^{\frac{k_n}{\gamma m} t} M_{n-2}(t)$$

$$\text{et } \lambda_n(t) = \frac{D}{\gamma^2} n(n-1) \int e^{\frac{k_n}{\gamma m} t} M_{n-2}(t) dt + d_n$$

$$\Rightarrow M_n(t) = \left[\frac{D}{\gamma^2} n(n-1) \int e^{\frac{k_n}{\gamma m} t} M_{n-2}(t) dt \right] e^{-\frac{k_n}{\gamma m} t} + d_n e^{-\frac{k_n}{\gamma m} t} \quad \textcircled{1}$$

• $n=1 \quad M_1(t) = 0.$

$$\Rightarrow M_3(t) = d_3 e^{-\frac{k_3}{\gamma m} t}.$$

$$\text{et } M_3(t=0) = \langle (x - \langle x \rangle)^3 \rangle = 0.$$

$$\Rightarrow \boxed{M_{2h+1} = 0}$$

①

• $n=2 \quad M_2(t) = d_2 e^{-\frac{k_2}{\gamma m} t} + \frac{Dm}{\gamma^2}$

$$\begin{aligned} M_2(t=0) &= \langle (x - \langle x \rangle)^2 \rangle = \langle x^2 - 2x\langle x \rangle + \langle x \rangle^2 \rangle \\ &= \langle x^2 \rangle - 2\langle x \rangle^2 + \langle x \rangle^2 = \langle x^2 \rangle - \langle x \rangle^2. \end{aligned}$$

$$\Rightarrow M_2(t=0) = 0$$

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$$\Rightarrow \alpha_2 + \frac{Dm}{\gamma k} = 0 \Rightarrow \alpha_2 = -\frac{Dm}{\gamma k}$$

$$M_2(t) = \frac{Dm}{\gamma k} \left[1 - e^{-\frac{2k}{\delta m} t} \right]$$

$$M_4(t) = \frac{D}{\gamma^2} 4 \times 3 \left\{ \int e^{\frac{4k}{\delta m} t} + \frac{Dm}{\gamma k} \left[1 - e^{-\frac{2k}{\delta m} t} \right] \right\} \times e^{-\frac{4k}{\delta m} t} + d_4 e^{-\frac{4k}{\delta m} t}$$

$$= \frac{12 D^2 m}{\gamma^3 k} \left[e^{\frac{4k}{\delta m} t} \times \frac{\delta m}{4k} - e^{\frac{2k}{\delta m} t} \frac{\delta m}{2k} \right] e^{-\frac{4k}{\delta m} t} + d_4 e^{-\frac{4k}{\delta m} t}$$

$$= \frac{12 D^2 m}{\gamma^3 k} \left[\frac{\delta m}{4k} \right] \left[1 - 2 e^{-\frac{2k}{\delta m} t} \right] + d_4 e^{-\frac{4k}{\delta m} t}$$

$$M_4(t=0) = 0 \Rightarrow \frac{12 D^2 \cdot m^2}{4 k^2 \gamma^2} + d_4 = 0 \Rightarrow d_4 = -\frac{3 D^2 m^2}{k^2 \gamma^2}$$

$$\Rightarrow M_4(t) = \frac{3 D^2 m^2}{k^2 \gamma^2} \left[1 - 2 e^{-\frac{2k}{\delta m} t} + e^{-\frac{4k}{\delta m} t} \right]$$

$$= \frac{3 D^2 m^2}{k^2 \gamma^2} \left[1 - e^{-\frac{2k}{\delta m} t} \right]^2$$

$$ii) M_2^p(t) = C_p [M_2(t)]^p$$

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$$\frac{dM_2^p(t)}{dt} = C_p p [M_2(t)]^{p-1} \frac{dM_2(t)}{dt}$$

$$\text{it } \frac{dM_2(t)}{dt} = -\frac{2k}{\delta m} M_2 + \frac{D}{\delta^2} 2(2-1)$$

$$= -\frac{2k}{\delta m} M_2 + \frac{2D}{\delta^2}$$

$$\Rightarrow C_p p [M_2(t)]^{p-1} \left[-\frac{2k}{\delta m} M_2 + \frac{2D}{\delta^2} \right]$$

$$= -\frac{k}{\delta m} \cdot 2p C_p [M_2(t)]^p + \frac{D}{\delta^2} 2p(2p-1) C_{p-1} [M_2]^{p-1}$$

$$= C_p p [M_2(t)]^p \left(-\frac{2k}{\delta m} \right) + C_p p [M_2(t)]^{p-1} \frac{2D}{\delta^2}$$

$$= C_p p [M_2(t)]^p \left(-\frac{2k}{\delta m} \right) + C_{p-1} p(2p-1) [M_2]^{p-1} \frac{2D}{\delta^2}$$

$$\Rightarrow C_p = C_{p-1} (2p-1)$$

$$\Rightarrow \boxed{C_p = C_{p-1} 2p-1}$$

(10)

$$C_1 = C_0$$

$$C_4 = C_3 \cdot \frac{7}{4} = \frac{7}{4} \cdot \frac{5}{2} = \frac{35}{8}$$

$$C_2 = C_1 \cdot \frac{3}{2} = \frac{3}{2}$$

$$C_3 = C_2 \cdot \frac{5}{3} = \frac{5}{3} \cdot \frac{3}{2} = \frac{5}{2} \dots$$

$$e) p(x, t) = e^{-\frac{M(t)}{2} x^2 + N(t)x + \Omega(t)}$$

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$$\frac{\partial p}{\partial t} = \left[-\frac{M'(t)}{2} x^2 + N'(t)x + \Omega'(t) \right] p$$

$$\frac{\partial p}{\partial x} = [-Mx + N] p.$$

$$\frac{\partial}{\partial x} \left[\frac{kx}{m\gamma} p + \frac{D}{\gamma^2} (-Mx + N)p \right]$$

$$= \frac{k}{m\gamma} \left[p + x \frac{\partial p}{\partial x} \right] + \frac{D}{\gamma^2} \left(-Mp + (Mx + N) \frac{\partial p}{\partial x} \right)$$

$$= \frac{k}{m\gamma} \left[p + x (-Mx + N)p \right] + \frac{D}{\gamma^2} \left(-Mp + (-Mx + N)^2 p \right)$$

$$= \frac{k}{m\gamma} \left[p - \underbrace{Mx^2 p + Nx^2 p} \right] + \frac{D}{\gamma^2} \left(-\underbrace{Mp} + \underbrace{M^2 x^2 p - 2NMx p + N^2 p} \right)$$

$$= p \left\{ \left(\frac{k}{m\gamma} - \frac{DM}{\gamma^2} + \frac{N^2 D}{\gamma^2} \right) + x \left(\frac{k}{m\gamma} N - \frac{D 2NM}{\gamma^2} \right) + x^2 \left(-\frac{k}{m\gamma} M + \frac{D}{\gamma^2} M^2 \right) \right\}$$

$$= p \left\{ -\frac{M'}{2} x^2 + N'x + \Omega' \right\}$$

$$\Rightarrow \begin{cases} -\frac{M'}{2} = -\frac{k}{m\gamma} M + \frac{D}{\gamma^2} M^2 \\ N' = \frac{k}{m\gamma} N - \frac{2D}{\gamma^2} NM \\ \rho' = \frac{k}{m\gamma} \rho - \frac{DM}{\gamma^2} + \frac{N^2 D}{\gamma^2} \end{cases} \quad (2)$$

b)

prozess: $\frac{dM^{-1}}{dt} = -M^{-2} \frac{dM}{dt}$

$$= -M^{-2} \left(-\frac{k}{m\gamma} M + \frac{D}{\gamma^2} M^2 \right)$$

$$= \frac{k}{m\gamma} M^{-1} - \frac{D}{\gamma^2}$$

$$\Rightarrow M^{-1}(t) = \lambda e^{\frac{k}{m\gamma} t} - \frac{D}{\gamma^2} \frac{m\gamma}{k}$$

$$= \lambda e^{\frac{k}{m\gamma} t} - \frac{mD}{k\gamma}$$

$$\bullet M^{-1}(t=0) = 0 = \lambda - \frac{mD}{k\gamma}$$

$$\Rightarrow M^{-1}(t) = \frac{mD}{k\gamma} \left[e^{\frac{k}{m\gamma} t} - 1 \right]$$

$$M(t) = \frac{k\gamma}{mD} \frac{1}{e^{\frac{k}{\gamma m} t} - 1}$$

(1)

III - Diffusion

a) Given $p_0(x, t | x_0) = \frac{1}{\sqrt{4\pi Dt}} e^{-\frac{(x-x_0)^2}{4Dt}}$ (1)

b) $\frac{\partial p}{\partial t} = D \frac{\partial^2 p}{\partial x^2} - \Omega p(x, t | x_0) + \Omega \delta(x-x_0)$ (0,5)

c) $\frac{\partial p(x, t)}{\partial t} = \int \frac{e^{-ikx}}{\sqrt{2\pi}} \frac{\partial \hat{p}(k, t)}{\partial t} dk$

$$\frac{\partial^2 p(x, t)}{\partial x^2} = \int \frac{e^{-ikx}}{\sqrt{2\pi}} (-k^2) \hat{p}(k, t) dk.$$

$$\delta(x-x_0) = \int e^{-ikx} \frac{e^{ikx_0}}{2\pi} dk.$$

$$\Rightarrow \frac{1}{\sqrt{2\pi}} \frac{\partial \hat{p}}{\partial t} = \frac{D}{\sqrt{2\pi}} (-k^2) \hat{p} - \frac{\Omega}{\sqrt{2\pi}} \hat{p} + \frac{\Omega}{2\pi} e^{+ikx_0} = 0$$

$$\Rightarrow -[k^2 D + \Omega] \hat{p} = -\Omega \frac{e^{ikx_0}}{\sqrt{2\pi}}$$

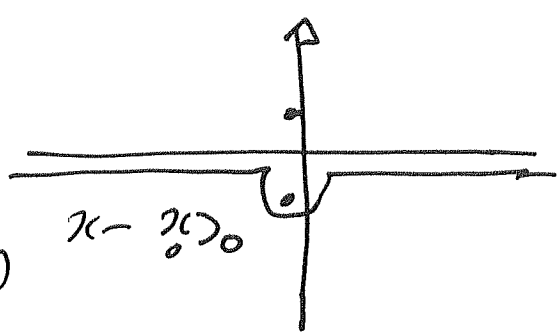
$$\Rightarrow \hat{p}(k, t) = \frac{1}{\sqrt{2\pi}} \frac{\Omega e^{ikx_0}}{k^2 D + \Omega}$$

$$p(x, t) = \int \frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{2\pi}} \frac{(\Omega e^{ikx_0})}{k^2 D + \Omega} \cdot e^{-ikx} dk$$

$$= + \frac{\Omega}{2\pi} \int \frac{e^{ik(x_0-x)}}{k^2 D + \Omega} dk.$$

• $k^2 D + R = 0$

$k^2 = -\frac{R}{D} \quad k = \pm i \sqrt{\frac{R}{D}}$



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$$p(x,t) = +\frac{R}{2\pi} \int_{-\infty}^{+\infty} \frac{e^{ik(x_0-x)}}{D(k+i\sqrt{\frac{R}{D}})(k-i\sqrt{\frac{R}{D}})} dx$$

For $x > 0$: $k = -i\sqrt{\frac{R}{D}}$

$$p(x,t) = \frac{R}{2\pi} \frac{2\pi i}{2\pi} \frac{e^{i(-i\sqrt{\frac{R}{D}})(x_0-x)}}{2i\sqrt{\frac{R}{D}} D} \quad x > x_0$$

$$p(x,t) = \frac{R}{2\pi} \frac{(-2\pi i)}{2\pi} \frac{e^{i(i\sqrt{\frac{R}{D}})(x_0-x)}}{2i\sqrt{\frac{R}{D}} D} \quad x < x_0$$

$$= \frac{1}{2} \sqrt{\frac{R}{D}} e^{\sqrt{\frac{R}{D}}(x_0-x)} \quad x > x_0$$

$$= \frac{1}{2} \sqrt{\frac{R}{D}} e^{-\sqrt{\frac{R}{D}}(x_0-x)} \quad x < x_0$$

$$p(x,t) = \frac{\alpha_0}{2} e^{-\alpha_0 |x-x_0|}$$

(2,5)

$$d) \underbrace{Q(0,t) = 0} \quad \text{et} \quad \underbrace{Q(x,0) = 1}$$

proba. de ne pas
voir alléger
au temps t étant
partir de x à $t=0$

proba. de ne pas
voir alléger
à l'instant t
étant partie de
 x à $t=0$.

$$q(x,s) = \int_0^{\infty} dt e^{-st} Q(x,t)$$

$$\begin{aligned} \bullet \int_0^{\infty} dt e^{-st} \frac{\partial Q}{\partial t} &= D \int_0^{\infty} e^{-st} \frac{\partial^2 Q}{\partial x^2} - r \int_0^{\infty} e^{-st} Q(x,t) \\ &\quad + r \int_0^{\infty} e^{-st} Q(x_0,t) \end{aligned}$$

$$\begin{aligned} \Rightarrow \left[e^{-st} Q \right]_0^{\infty} - \int_0^{\infty} dt (-s) Q e^{-st} \\ = D \int_0^{\infty} e^{-st} \frac{\partial^2 Q}{\partial x^2} - r \int_0^{\infty} e^{-st} Q(x,t) \\ + r \int_0^{\infty} e^{-st} Q(x_0,t) \end{aligned}$$

1 +

$$\Rightarrow \Delta q(x,s) = D \frac{\partial^2 q(x,s)}{\partial x^2} - r q(x,s) + r q(x_0,s)$$

$$\Rightarrow \left[D \frac{\partial^2 q(x,s)}{\partial x^2} = (r+s) q(x,s) = -1 - r q(x_0,s) \right]$$

$$e) \quad \mathcal{D} \frac{\partial^2 q(x, s)}{\partial x^2} - (n+1) q(x, s) = 0$$

$$\Rightarrow q'' - \frac{(n+1)}{\mathcal{D}} q(x, s) = 0$$

$$q(x, s) = A e^{dx} + B e^{-dx} + \frac{1+n q(x_0, s)}{n+1}$$

$$\hookrightarrow q(x, s) = B e^{-dx} + \frac{1+n q(x_0, s)}{n+1}$$

$$\bullet \quad Q(0, t) = 0$$

$$\Rightarrow q(0, s) = \int_0^\infty dt e^{-st} Q(0, t) = 0.$$

$$\Rightarrow B + \frac{1+n q(x_0, s)}{n+1} = 0.$$

$$\Rightarrow q(x_0, s) = - \left(\frac{1+n q(x_0, s)}{n+1} \right) e^{-dx_0} + \frac{1+n q(x_0, s)}{n+1}$$

$$\Rightarrow (n+1) q(x_0, s) = - (1+n q(x_0, s)) e^{-dx_0} + 1+n q(x_0, s)$$

$$q(x_0, s) = \frac{1 - e^{-dx_0}}{1+n e^{-dx_0}}$$

(2)

$$\begin{aligned}
 b) \quad T(x_0) &= - \int_0^{\infty} dt \, t \frac{\partial Q(x_0, t)}{\partial t} && (14) \\
 &= \left[t Q(x_0, t) \right]_0^{\infty} + \int_0^{\infty} dt \, Q(x_0, t) \\
 &= \int_0^{\infty} dt \, Q(x_0, t) \\
 &= q(x_0, s=0)
 \end{aligned}$$

$$\Rightarrow T(x_0) = \frac{1 - e^{-dx_0}}{R e^{-dx_0}} = \frac{e^{dx_0} - 1}{R} \quad (1)$$

g) (1)